

Push-Pull Phase-Splitter

New High-Gain Circuit

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THE advantages of resistance-capacitance circuits for phase-splitting in push-pull amplifiers are now well recognized, a wide variety of circuits for this purpose having been evolved in the last decade or so. If these circuits are investigated it is found that they possess varying degrees of merit in producing symmetrical output voltages, but share the common disadvantage of inherently low gain. In fact, low gain would appear to be almost inherent in any phase-splitting arrangement. The circuit to be described in this article, however, will be shown to possess a very high degree of symmetry with, at the same time, a large amplification from only two valves. An overall amplification of more than 1,000 times can very easily be achieved with standard low- g_m valves.

In order to facilitate analysis and to effect a just comparison with other types, the circuit will be compared with, and developed from, a normal cathode-follower phase-splitter preceded by a pentode A.F. stage.

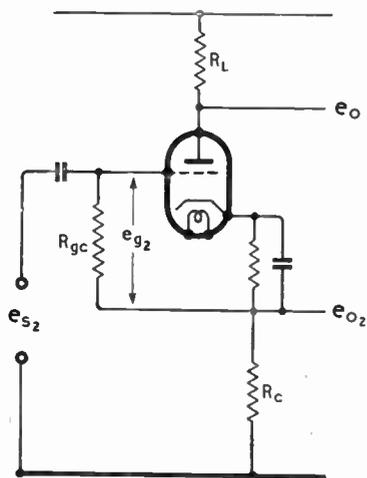


Fig. 1. The basic cathode-follower type of phase-splitter.

For the purposes of this article the amplification of a phase-splitting system will be regarded as the ratio of either output voltage (assuming the two to be sensibly equal) to the signal input

which limit the gain of the circuit of Fig. 2. It is well-known that the input impedance of a cathode-follower is extremely high, approximately $10 \times$ (impedance between grid and cathode); consequently if the grid-cathode impedance is made $250 \text{ k}\Omega$ the impedance to the right of "LM" in Fig. 2 is $2.5 \text{ M}\Omega$. In other words, the input circuit of V_2

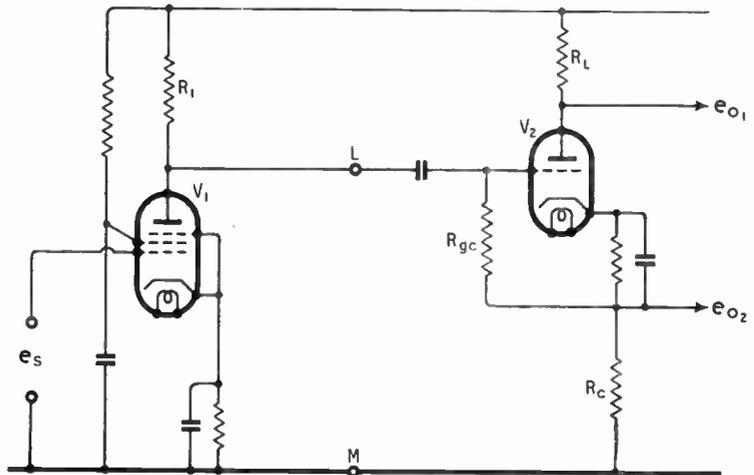


Fig. 2. The combination of a phase-splitter with a preceding A.F. stage is shown here.

voltage (i.e., amplification = $\frac{e_{o1}}{e_s}$

or $\frac{e_{o2}}{e_s}$ in Fig. 2). In other words, the gain of the system as a whole is twice that given. The cathode follower, Fig. 1, is perhaps the most generally used circuit because of its simplicity and the high degree of balance obtainable between e_{o1} and e_{o2} , at normal frequencies, being dependent, only on the accuracy of R_L and R_C . It possesses, of course, the inherent disadvantage of a cathode follower in that its gain is slightly less than unity (Appendix Equation (2)).

If we now consider such an arrangement to be preceded by a pentode stage the circuit becomes that of Fig. 2 and the overall gain is nearly that of the pentode alone, about 100 times.

Let us now consider the factors

does not appreciably shunt R_1 and the gain obtainable from V_1 is determined almost entirely by R_1 . The value of this resistance cannot, however, be increased indefinitely, owing to the fall in steady anode voltage of V_1 and a practical maximum is about $250 \text{ k}\Omega - 500 \text{ k}\Omega$. Since the A.C. resistance of the pentode is very high (say $2.5 \text{ M}\Omega$) it follows that only a small fraction of the amplification factor can be realized as gain (since gain = $\frac{\mu_1 R_1}{R_{a1} + R_1}$). This is unfortunate, because the amplification factor is extremely high, about 4,500 being quite a normal value for a pentode.

Suppose, however, it were possible to use the very high input impedance of a cathode-follower as the actual load on V_1 . Then, since this impedance

is comparable with the A.C. resistance of the pentode, the amplification obtained would be greatly increased.

$\mu_2 = 28$; with the component values of Fig. 4 Equation (1) gives the input impedance R_{in} as $2.05 \text{ M}\Omega$. It will be noted that

$$R_{gc} = \frac{R_1 R_3}{R_1 + R_3} = 168 \text{ k}\Omega.$$

Then the amplification of V_1 is given by: $\mu_1 \frac{R_{in}}{R_{a1} + R_1} = 2030$ (where $\mu_1 = 4.500$ and $R_{a1} = 2.5 \text{ M}\Omega$).

The gain of V_2 as given by Equation (2) is 0.9; therefore the

The inherent unbalance is less than 1.2 per cent. and therefore completely negligible. It may be wondered why any asymmetry should exist in the system; however, a consideration of the equivalent circuit of Fig. 6(b), shows that the sum of the alternating anode currents flows in the cathode load whereas the anode current of V_2 alone flows in the anode load. The ratio of the alternating components of the anode currents of V_2 and V_1 is, however, very large.

Design Considerations

The circuit was specifically developed to drive valves of the PX 25 class, and the values are therefore chosen to give a large peak output rather than maximum gain. If it is required to drive valves requiring a smaller grid swing no doubt much higher values of gain can be achieved. It should be pointed out to those evolving their own designs that the dynamic load on V_1 is very much greater than the D.C. load, while the A.C. load on V_2 is less than the D.C. load.

For smaller output voltages, say up to 25V R.M.S. at each output point, the component values are not critical while other

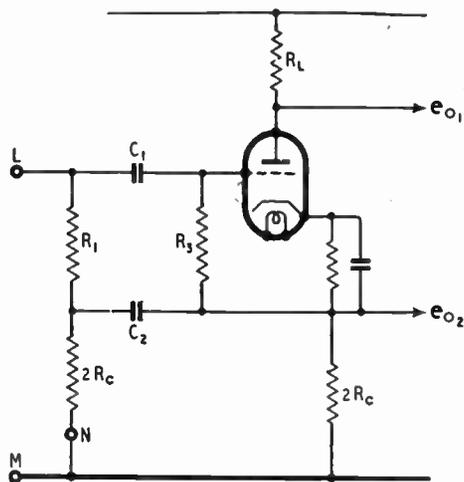


Fig. 3. A modified phase-splitter in which the coupling resistor R_1 becomes part of the grid-cathode impedance of the cathode-follower.

If the circuit to the right of LM in Fig. 2 is rearranged as shown in Fig. 3, the parallel impedance of R_1 and R_3 replaces the grid-cathode impedance R_{gc} while the effective cathode load is still R_c . Consequently the A.C. conditions have not been changed by the rearrangement and the input impedance is still approximately $10 \times R_{gc}$ (where $R_{gc} = \frac{R_1 R_3}{R_1 + R_3}$). It is assumed that the reactances of C_1 and C_2 are negligible at the lowest working frequency.

We cannot, as the circuit stands at present, connect the point L directly to the anode of V_1 since there is no means of supplying anode current to V_1 . It will be seen, however, that N is at earth potential and there is no reason why we should not return this end of the resistor to + H.T., which is also at earth potential, so far as A.C. is concerned. In this way we can provide a D.C. path to the anode of V_1 without disturbing the A.C. conditions on V_2 , while V_1 still sees the input impedance of V_2 , acting as a cathode follower, as its dynamic load.

The final phase-splitting circuit becomes that of Fig. 4, in which the component values are those used in the experimental model.

Using an EF 36 strapped as a triode for V_2 , $R_{a2} = 10 \text{ k}\Omega$ and

overall gain of the system $\frac{e_{o2}}{e_s} = 2030 \times 0.9 = 1860$. It is of interest to note that Equation (3) in the Appendix, which was derived directly from the equivalent circuit of Fig. 6(b), gives the same value as that obtained by the foregoing physical argument.

The degree of asymmetry between e_{o1} and e_{o2} must be regarded

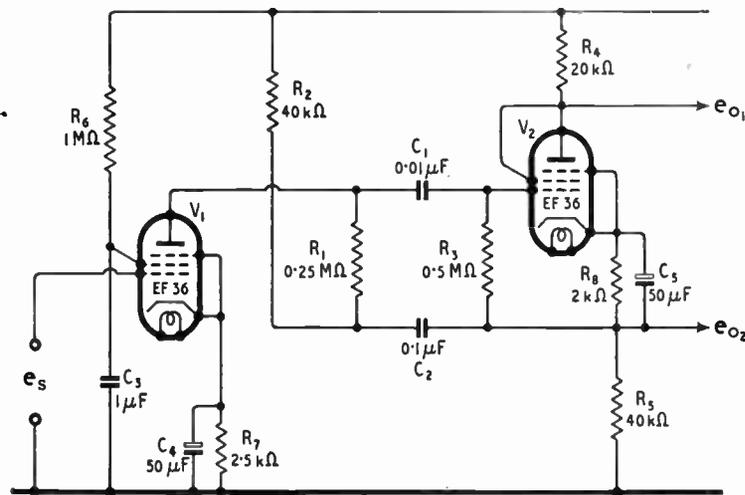


Fig. 4. The practical form of the high-gain phase-splitter and preceding stage.

as of even greater importance than mere gain. Inserting numerical values in Expression (4) of the Appendix we obtain $\frac{e_{o1}}{e_{o2}} = 0.989$.

types of valve have been substituted with only minor circuit changes; e.g., bias and screen resistors. It is of interest to note that the EF.36 strapped as a

Push-pull Phase-splitter—

triode gave better results from a linearity point of view than any of the triodes investigated.

As with most cathode-follower systems, it is advisable to reduce the heater-cathode voltage of V_2 by using a separate heater supply for the stage, connected to an appropriately decoupled point on the H.T. supply.

In order to avoid loss of gain it is desirable to by-pass the cathode bias resistors of each stage.

Table I gives the results obtained with the circuit of Fig. 4.

TABLE I

H.T. Supply Voltage	Max. output Voltage e_{o1} (or e_{o2})		Input Voltage for max. output (R.M.S.)	Gain
	R.M.S.	Peak		
400	37.5	53	0.031	1210
290	25.6	36	0.023	1110

It will be noted that the measured gain is somewhat less than the calculated value, the discrepancy is not however more than can be accounted for by variations in the actual values of components from those assumed.

Application of Circuit

The circuit has been used over a number of years in a wide

A complete design is given in Fig. 5. KT 66 valves strapped as triodes have been used in the

$120/n^2$ ohms. It is illuminating to note that this latter value is less than that obtained by opera-

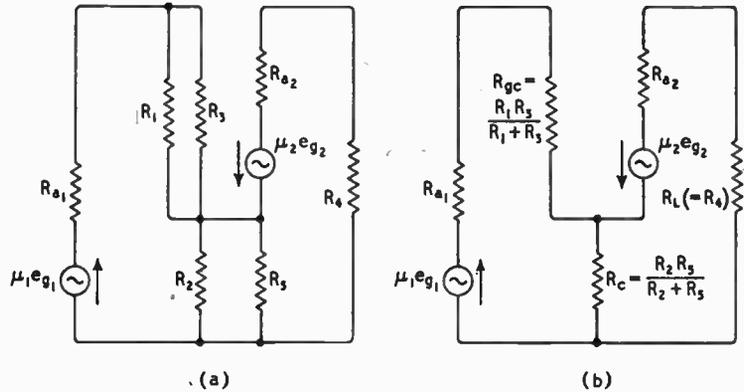


Fig. 6. The equivalent circuit of Fig. 4 can be drawn in the forms shown at (a) and (b).

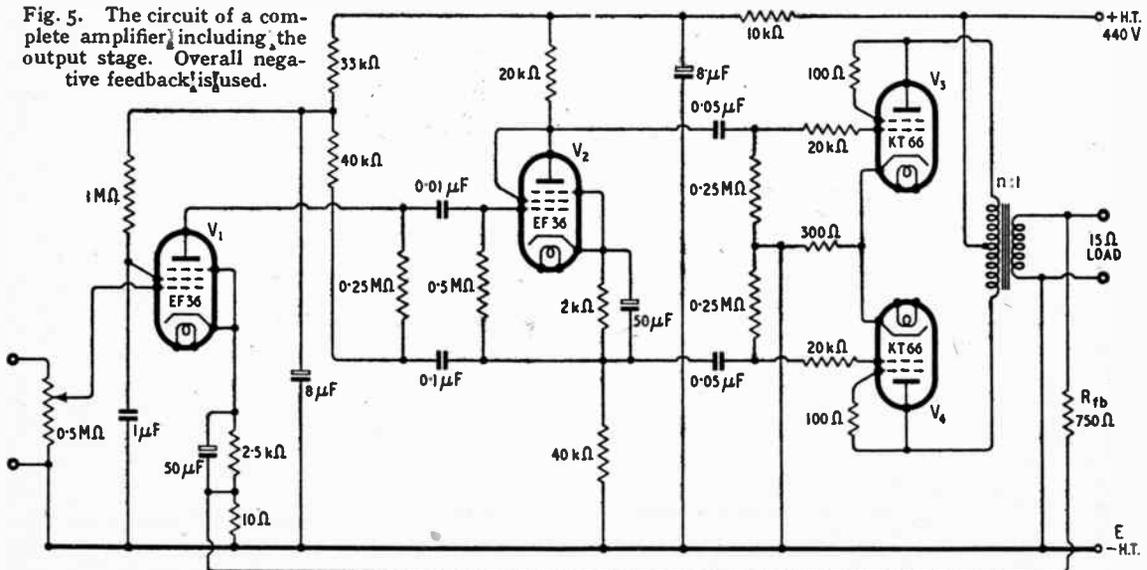
output stage, this method of connection giving a performance roughly equivalent to that of the PX25 type with the added advantages of shorter grid swing, indirectly-heated cathodes and octal base.

Without negative feedback an output of 14.5W is obtained with less than 0.025V (R.M.S.) input. If negative feedback is applied as shown in Fig. 5 the required input voltage for maximum output is raised to 0.25V (R.M.S.). The negative feedback reduces

the same valves as a cathode-follower stage. Using a good quality output transformer the response, with overall negative feedback, was measured to be within ± 1 db from 25–20,000 c/s. If an output transformer of poorer quality is used the degree of feedback may have to be slightly reduced in order to satisfy the Nyquist stability criterion.

Where a greater output is required the KT 66 valves can be operated as tetrodes in the normal manner and 35 W can

Fig. 5. The circuit of a complete amplifier including the output stage. Overall negative feedback is used.



variety of amplifiers and has proved to be remarkably stable and free from undesirable traits.

the distortion content to 0.5 per cent at maximum output, while the output impedance becomes

then be obtained. The author favours however the use of four valves operating as triodes in

parallel push-pull where a large output is desired.

No originality is claimed for the circuit, as a search of the literature has shown that it appeared in the U.S.A. some years ago; however, so far as the author is aware no analysis of the circuit has previously been published.

APPENDIX

The input impedance of the cathode-follower phase-splitter of Fig. 1 is well known to be:

$$R_{in} = \frac{R_{a2} + (\mu_2 + 2)R_L}{R_{a2} + 2R_L} \times R_{gc} \quad \dots (1)$$

when $R_L = R_0$

If, as is frequently the case, $R_L = R_c \approx R_{a2}$ then $R_{in} \approx \frac{\mu_2 + 3}{3} \times R_{gc}$.

For a triode, with μ_2 between 20 and 30, $R_{in} \approx 10 R_{gc}$.

The amplification is given by:

$$\frac{e_{o1}}{e_{s2}} = \frac{e_{o2}}{e_{s2}} = \frac{\mu_2 R_L}{R_{a2} + (\mu_2 + 2)R_L} \quad \dots (2)$$

If again $R_{a2} = R_L$ this becomes

$$\frac{\mu_2}{\mu_2 + 3}$$

Then if $\mu_2 = 20$, gain ≈ 0.9 .

Amplification of Pre-amplifier and Phase-splitter Together.

The equivalent circuit of Fig. 4 is shown in Fig. 6(a) and 6(b). e_{g2} is the voltage developed across R_{gc} . Taking into account the sign of this voltage e_{o1} and e_{o2} can be found in terms of e_{g1} ($= e_s$) and e_{o1}/e_{o2} represents the degree of unbalance of the system.

By writing the basic circuit equations from Fig. 6(b) expressions for amplification and unbalance are readily obtained. Thus if $R_L = R_c$:

$$\frac{e_{o2}}{e_s} = \frac{\mu_1^2(\mu_2 R_{gc} - R_c)}{(R_{a1} + R_{gc} + R_c) \left(\frac{R_{a2}}{R_{gc}} + 2 \right)}$$

$$\text{and } \frac{e_{o1}}{e_{o2}} = \frac{\mu_2 R_{gc} - R_c}{\mu_2 R_{gc} + R_{a2} + R_c} \quad \dots (4)$$