SPEAKING CLOCK

BY STEPHEN HUNT I SPEAK YOUR DATA

In the beginning was the Word ... and time began. Seconding the SPO256AL speech chip to verbalise the output of a real-time clock may be a less momentous event, but it continues an ancient and honourable tradition!

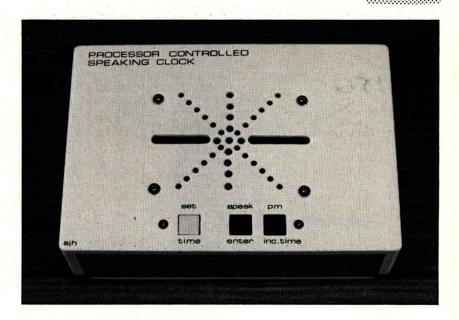
Many articles have been designed around the SPO256AL speech synthesiser. However, the majority of them have been simply for experimentation in conjunction with a home computer and serve no real application. This article describes how the allophone speech system can be used to produce a speaking clock which may be invaluable to a blind person or simply a novelty clock demonstrating the use of current electronic devices.

The block and circuit diagrams are shown in Fig.1. The system forms a simple microprocessor controller which is used to process data from the real time clock. The speaking clock uses a 6802 micro-processor in conjunction with a 2716 eprom, 6821 pia and an ICM7170 real time clock. The heart of the system is the program stored in the rom.

MEMORY MAP

The eprom occupies locations 8000H to 87FFH (2K). The address decoding for IC3 uses A15 via an inverter IC6a when the eprom is enabled low. The pia, IC2, is selected by A14 and A2, corresponding to location 4004H. To prevent the pia and eprom being selected at the same time A15 is also connected to CS2. RS0 and RS1 are connected to A0 and A1 respectively and are used to select internal registers which control port operations. The pia places the speech synthesiser in the memory map.

It might appear at first that using a pia to interface with IC4 and a few switches is over complicating matters. Alternatively, octal buffers such as the 74LS244 type of devices could be used but would require extra decoding logic, take up more room and cost more. The 6821 has three select lines (CS0, CS1 and CS2) which can be connected to appropriate address lines to place it in the memory map, and allows for a much simpler approach. The 6821 also contains two user ports, A and B which can be set by software as inputs or outputs as required. The speaking clock program requires PA0 to PA6 to be outputs and PA7 to be an input line. Port B lines are all set as inputs. Port A controls the



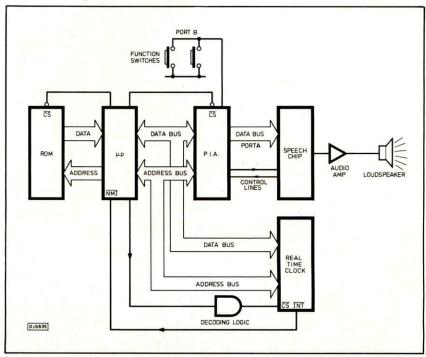
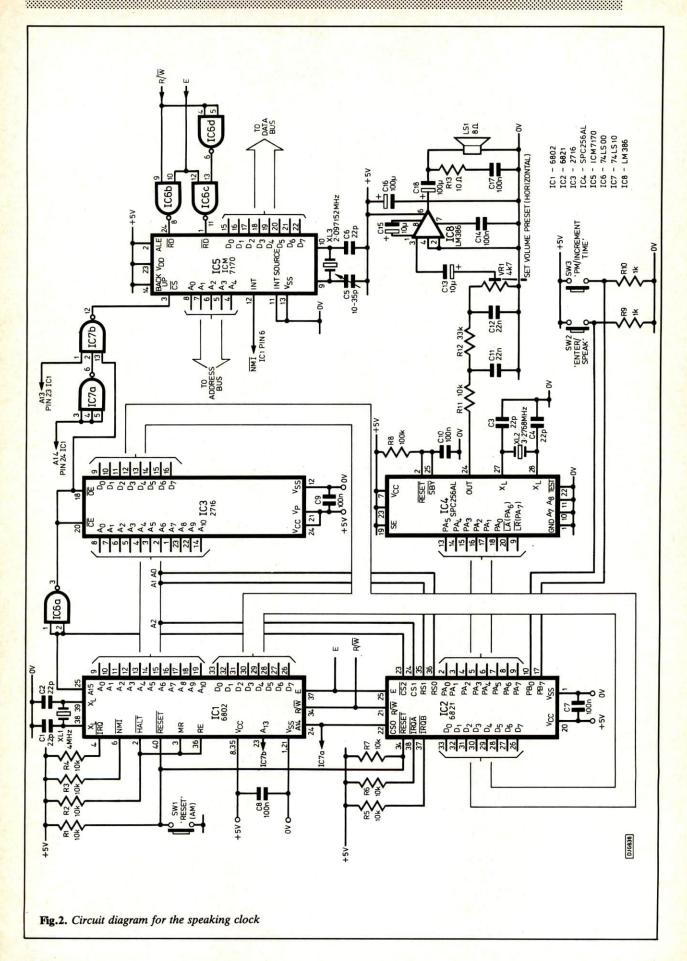


Fig.1. Block diagram for the speaking clock



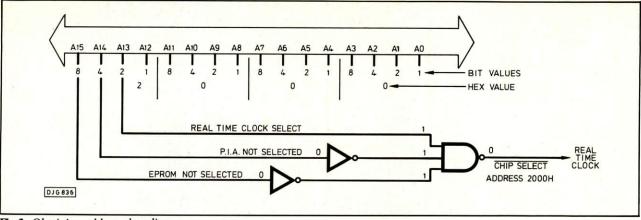


Fig.3. Obtaining address decoding

speech synthesiser while port B looks at the function switches, S2 and S3.

The real time clock, IC5, sits at location 2000H and is selected by IC7 from address lines A13, A14 and A15. Fig.3 shows how the decoding is obtained. All other decoding is done in a similar way.

The speaking clock uses a small amount of ram for data storage and as a stack for holding return addresses when jumping to subroutines. This ram is contained within the 6802 at locations 0000 to 007FH (128 bytes).

It should be realised that the devices are only partially decoded and therefore appear in several blocks in memory. However, as only three locations are decoded in the 64K area, this causes no problems of accidental enabling and is therefore perfectly acceptable.

SPEAK TO ME

Words are generated by stringing together allophones which make up the basic sounds of speech. By carefully selecting them a fairly reasonable quality of speech can be produced bearing in mind the limitations when compared to digitally encoded voice systems.

The data control (handshaking) is performed by two lines, load address and load request. When the synthesiser is ready for data the load request line is held low. Then the allophone data is placed onto the bus and by taking the load address low latches the data into the chip. While it is speaking (busy) the load request line is taken high and only when it goes low again can you send the next data. The processor looks at PA6 and PA7 of IC2 to control the data flow.

The speed or pitch at which it speaks is governed by XL2. The prototype used a 3.2768 MHz crystal but any value in the range of 3 to 3.5 MHz will do. The output from IC4 is pulse width modulated at 20kHZ and this is removed by a low pass filter formed by R11, C11, R12 and C12. The resulting audio is then amplified by a small power amplifier, IC8, to drive a loudspeaker.

No allophone data has been given

here as many readers will have probably come across this device before. (Allophone Data Principles were discussed in the MicroChat article in PE Sept-Oct 87. Ed.)

KEEPING TIME

In order to keep track of the time a real-time clock is used. This device contains an onboard oscillator and a series of registers which contains data for hours, minutes, seconds etc. These registers are simply cascaded upcounters, ie, the seconds counter sequences from zero to sixty then the carry-out from this counter increments the next, which in this case is the minutes. The counters can be preloaded to any value before the oscillator is enabled. Each register has an address and by sending data to that address the counter is loaded. The hours counter is a programmable divider which can be set by software to divide by 12 or 24 (12 or 24 hour mode). The real-time clock is completely independent from the processor and is free running. The processor simply preloads the registers with time data and starts the clock. By reading the register addresses the processor can obtain the time which the program then sorts out to provide the speech synthesiser with word data.

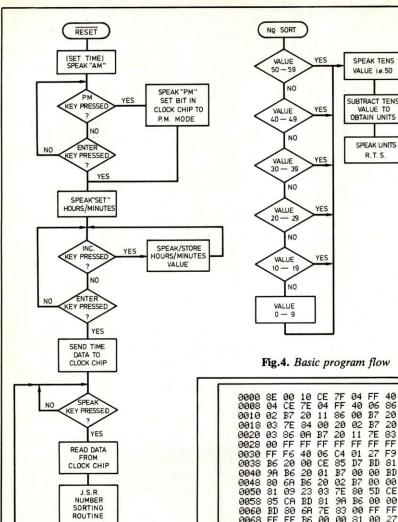
When the processor has finished reading data from the real-time clock it scans the function switches. Not exactly doing too much, is it? This may seem rather a waste of processing power. Alternatively, you could use the processor to keep time by using its internal registers as programmable dividers. This however, requires several processor registers which are not being used for data manipulation and as the 6802 has only three working registers this is not feasible. The use of a real-time clock reduces the program length and complexity substantially.

The ICM7170 real-time clock was chosen mainly because it is easy to use. It is completely software controlled and has a total of 18 internal registers. The main register of interest is the command register which is used to set up operation modes. Table 1 shows the assigned bits.

Bits D0 and D1 set the internal clock frequency. In the prototype a 2.097MHz crystal was used but others can be accommodated by making the program changes shown in Table 2.

D2 is set to zero for 12 hours. Stopping and starting of the clock's counters is obtained by writing a 0 or 1 respectively into the bit location. D4 sets up interrupts for alarms and D5 is used as a test bit which clocks the counters at a faster rate. D5 and D7 are not used.

D7	D6	D5	D4	D3	D2	D1	D0
	dou le d in	TEST	INT	RUN	12/24	FREQ	FREQ
Table 1							
CRYSTAL FREQ		D0	D1	PROGRAM CHANGES			
32.768	кнг		0	0	0010 04BC	00 08	
1.048576MHz			0	1	0010 04BC	01 09	
2.097152MHz		1	0	ASIN	HEX LIST		
4.194304MHz		1	1	0010 04BC	03 0B		
Table 2							



The ICM7170 was not specifically designed for the 6800 series of microprocessors. The device has both active-low read and write lines. IC6B to IC6D gate the processor's E line with the r/w line to provide IC5 with the required RD andWR signals. A simple inverter cannot be used between the two lines as this would not take into account the r/w timing cycle. In order to synchronise the r/w signals with the processors clock, 02 of the clock cycle ('E' line) is also gated with the r/w line.

PROGRAM OPERATION

DJG837

After switching on you need to set up the time. By pressing 'SETTIME' the clock will say "AM". Pressing 'INC' sets to pm, or pressing 'ENTER' causes it to say "SET HOURS". By pressing 'INC' the hours are spoken in turn (1 to 12). When the required hour has been spoken pressing 'ENTER' stores this value in the hours register. It then says "SET MINUTES". Pressing 'INC' then advances the tens of minutes (10, 20, 30, 40, 50). When the required value has

 0000
 SE
 00
 10
 CE
 FF
 40
 66
 86

 0008
 04
 CE
 7E
 04
 FF
 40
 06
 86

 0010
 02
 B7
 20
 11
 86
 00
 B7
 20

 0020
 03
 7E
 84
 00
 20
 02
 B7
 20

 0020
 03
 FF
 <

9A F6 20 84 80 81 81 FF 400 80 87 95 96 CE7 80 CE7 F50007101E900F6006603046660440564000161E900FFFFFFFFFFF60000444444F1F0000F687FF0010 FF 860 80 2E BB 80 CE 00 0300 0308 0318 0320 B6 4A 85 BD 00 85 0338 0340 0360 FF 40 06 CE 40 06 03 BD 1E 80 00 1 B7 06 60 5E 00 0400 0408 0410 0428 0430 0438 0440 0448 0458 0460 0478 0480 BD 27 C4 Ø8 0490 0498 04A0 04B8 04C0 04C8 04D0 04D8 04E0 04E8 04F0 9599 9598 9519 9518 9529 9528 ØD 13 04 04 04 05 07 08 04 13 04 13 04 13 13 13 13 13 13 13 13 14 0530 0538 0540 0548 0550 0558 0560 0568 0578 0580 0588 0590 0598 05A0 05A8 0580 0588 0500 0508 FF 04 FF 38 24 33 FF 28 F 04 04 33 70 1 FF 80 05D0 05D8 05E0 05E8 05F0 9698 9619 06B0 06B8 94 37 97 **0608** 06D0 ØD

Fig.5. Hex dump of the speaking clock program

SPEAKING CLOCK

been spoken pressing 'ENTER' stores this value in a location in ram. Pressing 'INC' now advances the units (1 to 9). Pressing 'ENTER' stores this value in a second location in ram. Adding these two locations together gives the total minutes value which is then stored in the minutes register. The program now jumps to a routine which looks to see if the 'SPEAK' key has been pressed.

On pressing the 'SPEAK' key the 100ths second register is read. This latches the time data to prevent it rolling when reading the various time data registers. The hours register is read and the program jumps to another routine which determines the hour value. Having done this it now jumps to the next routine which sends the required word data to the speech synthesiser. Now the clock has to speak the minutes. To explain this it is best to look at an example.

Suppose the minutes value is 46, the routine determines the group value, which in this case lies between 40 and 49, and so "forty" is sent to be spoken. To obtain the unit value (six) forty is subtracted and "six" is sent to be spoken. Fig. 4 shows the program flow.

A routine also sorts out the grammar. If the minute value is less than ten "OH" has to be spoken before the units value and if zero it has to say "O'CLOCK". (Was Victor Borg consulted about the correct pronunciation of the apostrophe? Ed.)

If the time lies between 1:00am to 11:59am it will say "GOODMORNING THE TIME IS.....". Between the times of 12;00noon to 5:00pm it says "GOODAFTERNOON THE TIME IS....." and from 6:00pm onwards it says "GOODEVENING THE TIME IS.....".

The machine code listing is shown in Fig.5 and occupies approximately 1K of code. If any readers might like to enhance or write their own programs, the addresses in Table 3 may be of use.

FINDING THE STORED PROGRAM

When the processor is reset it looks at the reset vector addresses FFFEH and FFFFH and reads the data at each location. These two bytes are loaded into the processor's program counter and is used as a start location from which to run. As the eprom sits at memory location 8000H this must be the address held in the program counter.

On looking at the hex listing we see that the reset vector address is stored in locations 07FEH and 07FFH and not the required addresses FFFEH and FFFFH! This is easily explained. As the eprom is only 2K * 8 (16K) address lines A0 to A10 are all that are needed to access any location within it. Therefore the bit values A11 to A14 are not seen (A15 selects the eprom). When FFFEH is sent out by the processor A11 to A14 are 'lost'

	REGISTERS	ADDRESS
REALTIME CLOCK	1/100THS	2000H
	HOURS	2001H
	MINUTES	2002H
	SECONDS	2003H
	MONTHS	2004H
	DATE	2005H
	YEAR	2006H
	DAYOFWEEK	2007H
	COMMAND REGISTER	2011H
SPEECH SYNTHESISER	4004H	
FUNCTION SWITCHES	4006H	
Table 3		

and the processor sees the contents of address 07FEH instead. This is of no consequence as long as the processor obtains the correct start location.

CONSTRUCTION

A suggested power supply is shown in Fig.6.

The majority of components fit onto a double sided pcb, the layout of which is shown in Fig.7. It is recommended that sockets are used for all ic positions, especially IC3 which may be required to be replaced with different versions of software. Also note the capacitor polarities around IC8. A soldering iron with a small bit is required for construction as many tracks run extremely close together and are very easily bridged by solder. Before fitting any components to the pcb make all the through hole connections using fine single strand wire. (Better still, use pc link pins. Ed.) Care should be taken to ensure all these connections are made as there are quite a few, many being under components. Construction can now continue in the usual manner.

The unit was housed in a Verobox type 75-1411D. The back panel is used as a chassis onto which the transformer is bolted. It also serves as a heatsink for the regulator (IC9). The mains lead passes through a grommet and is secured by a 'P' clip fixed to the base of the box. The earth wire is soldered to a tag bolted to the transformer fixings. A few 3mm holes are drilled in the base under the transformer to aid ventilation.

The pcb is fixed to the base by spacers. Make sure that the far side of the pcb sits flush against the back panel so that the regulator can be bolted to it. Terminal pins should be used where wires connect to the board. This makes the board easier to remove, and looks neater.

The speaker is attached using four M4*10 csk screws. The speaker should be as large as possible (at least 3in) to provide a good frequency response. Rub on transfer letters can be used to label switch functions and lacquer applied to fix them.

TESTING

After checking the board construction and wiring connect a voltmeter (set to 10V range) across C19. The rough dc should be around 7.5V (minimum). Check from 5V on the output of IC9. Press 'SETTIME'. It should respond by saying "A M". If nothing happens recheck your wiring. If you programmed your own eprom check it for errors. Also make sure that the rom is being addressed (selected) by monitoring IC3s chip-select pin, which should be low. (A15 should be constantly high).

Adjust C5 to obtain an accurate clock time. By trial and error an accuracy of few seconds a day is possible. An alternative method is to write a piece of software which causes the realtime clock to produce an interrupt every second. The interrupt signal can then be monitored with a frequency counter (negative side triggered) and C5 adjusted for a reading of 1.0000000 on the display. The first method is accurate enough although more time consuming.

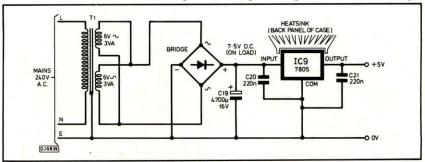
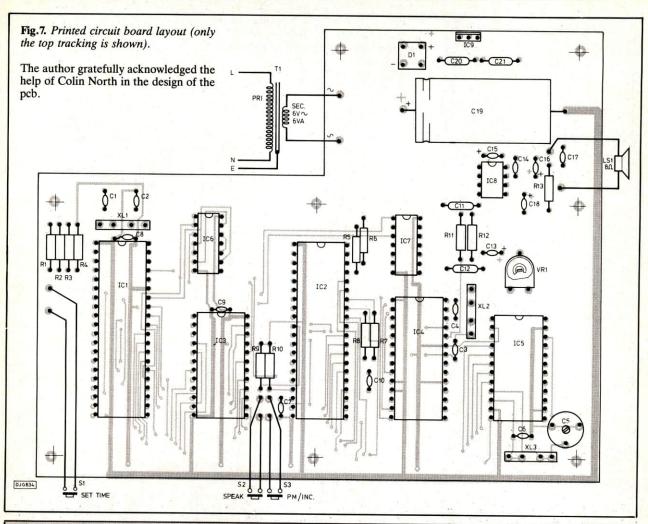


Fig.6. Power supply circuit diagram



COMPONENTS		SEMICONDUCTORS		CONSTRUCTOR'S NOTE	
RESISTORS R1-R7 R9,R10 R8 R12 R13 All resistors 1/3 W CAPACITORS C1-C4,C6	10k (8 off) 1k (2 off) 100k 33k 10Ω stors 1/3W 5%.	D1 IC1 IC2 IC3 IC4 IC5 IC6 IC7 IC8 IC9	Bridge rectifier 2A 50V 6802 6821 2716 (5V) SPO256AL ICM7170 74LS00 74LS10 LM386 (6V version) 7805	One of Stephen's friends has very kindle offered to program any blank eprome sent to him in connection with the project. Send your eprome with stamped addressed envelope (of equivalent return postage) to: Charles Moore, 101 Heatherstone Avenue, Dibden Purlieu, Hythe, Hants, SO4 51.F.	
C5 C7-C10,C14,C17 C11,C12 C13,C15 C16,C18	10-35pF variable 100nFceramic (6 off) 22nFpolyester (2 off) 10µF16Velect (2 off)	POTENTIOMETER VR1 4k7 horiz preset		(please state value of crystal being use in the real-time clock).	
C19 C20,C21	100μF 16V elect (2 off) 4700μF 16V elect 220nF polyester (2 off)	CRYSTALS XL1 XL2 XL3	4MHz 3 to 3.5MHz (see text) (see text)	CONSTRUCTOR'S NOTE The double sided printed circuit board is available through the PE PCB Service, see page 60.	
		MISCELLANI	EOUS		

0-6V, 0-6V

SP push make

switches (3 off)

winding

transformer 3VA per

Vero type 75-1411D $(20.5 \times 14 \times 7.5 \text{cm})$

8 ohm 3in speaker

T1

S1,S2,S3

Pcb, sockets, wire etc.

Case

STEPHEN HUNT

While preparing Stephen's article for publication, we were distressed to learn of his tragic death. It is his parent's wishes that we should still publish his article. We send our deepest sympathy to his family. Ed.

If you are unable to set up the clock fairly accurately then this is probably due to the crystal not being loaded correctly. Inserting the specified load capacitor (C6) for the crystal should cure the problem. Finally set VR1 to the volume required.



STATIC SENSITIVE

During bench testing of the prototype, it was discovered that the realtime clock's interrupt pin was prone to static charges. When "zapped", the chip latches up and draws excessive current.

This is due to the fact that the interrupt line does not have the normal protection diodes found in most cmos devices. As long as the relevent pcb tracks are not touched by "aerials" such as screwdrivers etc, no harm should result.

It was felt that adding components to suppress transients could prove to be more trouble than it's worth and as these components are not integrated on the silicon itself would only provide limited protection. However, once the board is housed in an enclosure the chance of latch up is reduced to zero. The prototype has been working faultlessly for many months.

Please take care when bench testing!

