

# Add a manual reset to a standard three-pin-reset supervisor

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Adding a manual reset to a design usually involves designing in a new part with a manual-reset input. But, by adding a couple of low-value resistors, a standard three-pin-reset supervisor can work in most applications. The circuit in **Figure 1** ensures a clean  $\overline{\text{RESET}}$  signal during and after you have pressed the manual-reset button. When you activate the manual-

reset button, the supply voltage drops below the reset supervisor's minimum reset threshold because of the  $R_1/R_2$  voltage divider formed when  $S_1$  is active. This action causes the reset supervisor to activate its  $\overline{\text{RESET}}$  output. When you release  $S_1$ , the supply voltage returns to above the reset-supervisor maximum-reset threshold, and  $\overline{\text{RESET}}$  remains active for the time-

out period of the reset supervisor.

When you do not press  $S_1$ ,  $R_2$  has a voltage drop arising from the reset supervisor's supply current and  $\overline{\text{RESET}}$  output loading. For most reset supervisors, the maximum supply current is  $50\ \mu\text{A}$ . For most designs, the  $\overline{\text{RESET}}$  output goes to one or more CMOS inputs that require about  $10\ \mu\text{A}$  each. With two CMOS devices connected to  $\overline{\text{RESET}}$ , the total current through  $R_2$  would be  $(2 \times 10\ \mu\text{A}) + 50\ \mu\text{A} = 70\ \mu\text{A}$ . The voltage drop across  $R_2$  due to the current flow effectively adds  $70\ \mu\text{A} \times 100\ \Omega = 7\ \text{mV}$  to the reset su-

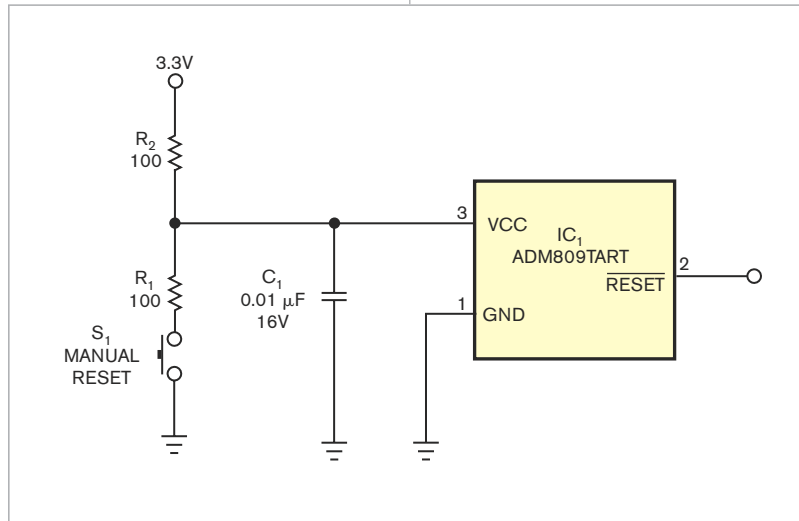
pervisor's reset-threshold voltage.

You should consider several trade-offs for the selection of values for  $R_1$ ,  $R_2$ , and  $C_1$ . The value of the local bypass capacitor,  $C_1$ , for the reset supervisor should be low enough to allow the reset supervisor to detect transient supply-voltage drops. The time constant of  $R_2$  and  $C_1$  determines this factor; in this example, the time constant is  $100\Omega \times 0.01\ \mu\text{F} = 1\ \mu\text{sec}$ . This figure is typically much higher than the decay rate of a regulated power supply that has lost power.

When you activate  $S_1$ , current flows through  $R_1$  and  $R_2$ . In the circuit in **Figure 1**, the current flow when you activate  $S_1$  is  $3.3\text{V}/(100\Omega + 100\Omega) = 16.5\ \text{mA}$ . This amount of current would be OK for a line-powered system but may not be OK for a battery-powered system. You can reduce the current by increasing the value of  $R_1$  and ensuring that the reset supervisor's supply voltage drops below the minimum reset threshold. You can also increase

the value of  $R_2$ , along with that of  $R_1$ , but doing so will cause increased voltage drop and slower response to transients. Note that the increased current

of the manual reset occurs only while the manual reset is active, and typical system current drops while  $\overline{\text{RESET}}$  is active.**EDN**



**Figure 1** A pair of low-value resistors, a capacitor, and a pushbutton add a manual-reset function to a standard three-pin-reset supervisor.