

# PC Hardware Interfacing Part 10

Last month we got the PC serial card working internally, but left it without any way to communicate with the outside world. This time around we'll have a look at finishing up the hardware involved in adding this useful facility to the design.

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**D**espite the obvious importance of doing so, making our emerging serial card actually able to communicate with external devices is pretty simple. There's no complex binary math to concern ourselves with, and really very little hardware. Of course, the hardware is a bit obtuse, but this is to be expected when one is dealing with a fifty year old standard.

The only tricky thing about serial communications is that it's designed to work with hardware which really predates microcomputers by quite a long while. Whereas everything inside a computer uses predictable logic levels and timing, serial data is a world unto itself. Regrettably, it's something which must be endured, having become entrenched in our universe.

## Bilevel Tuba Solo

The first serial devices were teletypes, which puts the origin of this form of communication back several decades. Early teletypes were wholly mechanical, with lots of solenoids and relays and numerous other things too arcane and horrible to contemplate. They did use these devices to

synthesize a crude form of electronic logic, however. A teletype took keyboard input, translated it to serial data, sent said data over wires and ultimately turned it into hard copy at the far end of the line.

Big, clunky solenoids that can drive an old style print mechanism do not run cheerfully on five volts. For various reasons, the logic levels of those old teletypes, and hence of our modern serial communications, were such that a positive voltage was considered to be one and a negative voltage zero. Zero volts... and, in fact, anything within several volts of it... was and is undefined.

The original range was forty-eight volts either side of zero. Contemporary serial devices use twelve volts. However, because of the way this system is structured, anything beyond three volts positive is considered to be a logic level of one, and anything beyond three volts negative is a logic level of zero. As such, some devices use plus and minus five volts and get away with it.

The advantage of this bipolar system is actually fairly apparent. Devices which use differing voltage levels can communi-

cate without specialized line drivers. In addition, bipolar logic levels can live with a great deal more voltage loss because of line resistance before they start losing data. This isn't much of a problem now unless you'll be driving serial data over fifty feet of cable, by it impressed the teletype guys to no small end way back in the middle ages.

The only real problem facing the hardware we're about to look at, then, is converting the PC's TTL logic levels to these rather more obtuse ones and back again. As we'll see, there are special parts to do this for us. The 1488 and 1489 chips... as are found in just about every microcomputer serial port design... conveniently change TTL logic levels to serial port logic levels and back again.

The actual serial lines to be interfaced are something of a wonder as well, once again dating back into the mists of prehistory. In theory, serial data can be managed using only three lines, one of which is ground. Labeled TXD and RXD on our schematic, these things send and receive serial information respectively. As long as the hardware at the other end of the serial



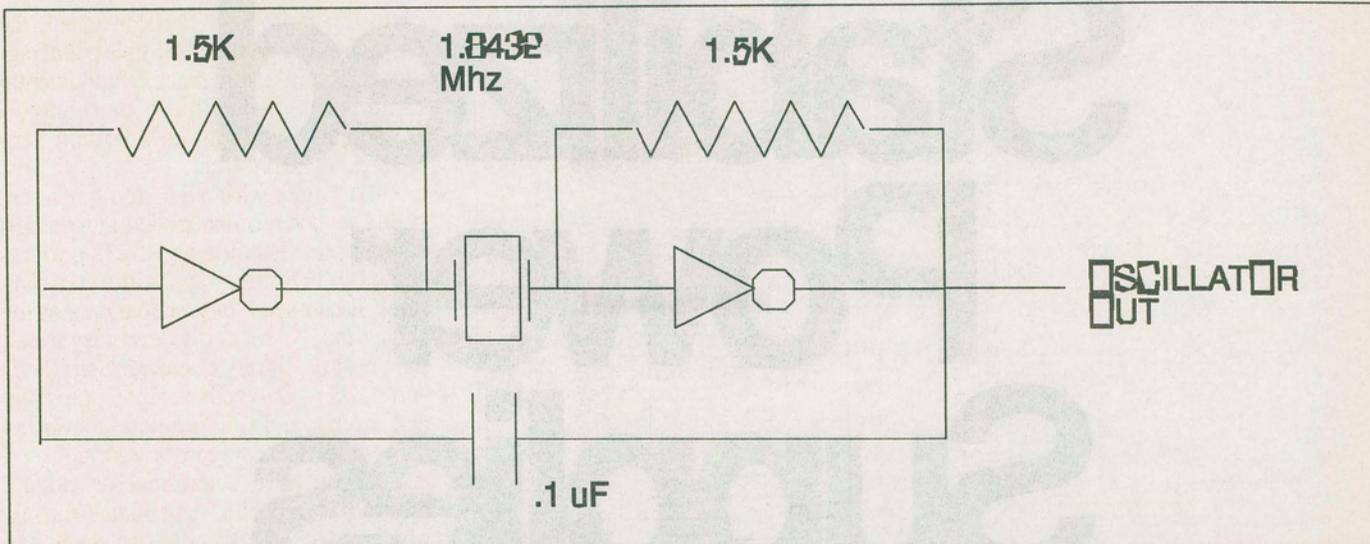


Figure 2. A crystal controlled oscillator to drive the 825D serial port circuitry.

```
OUTDX,AL;SETHIGHORDERBAUD
```

```
MOVDX,3FBH
MOVAL,1AH
OUTDX,AL;SETCFW
```

We'll get into how this works in more detail later on.

Next, we have to create the basic terminal loop. This is what it looks like.

```
T_LOOP:MOVDX,3FDH
INAL,DX;GETTHERXPORTSTATUS
TESTAL,1;ISBITSETFORBYTEWAITING?
JZT_KEY;IFNOT,CHECKTHEKEYBOARD
```

```
MOVDX,3F8H
INAL,DX;IFSO,GETTHEBYTEFROMPORT
```

```
ANDAL,7FH;MASKOFFANYGARBAGE
```

```
MOVDL,AL
MOVAH,2
INT21H;PRINTTHECHARACTER
```

```
T_KEY:MOVAH,1
INT16H;ISTHEREAKEYWAITING?
JZT_LOOP;IFNOT,CHECKTHEPORTAGAIN
```

```
MOVAH,0
INT16H;IFSO,FETCHIT
```

```
MOVDX,3FBH
OUTDX,AL;SENDITOUT
```

```
JMPT_LOOP;GOLOOPAGAIN...ANDAGAIN...
```

This is a very simple terminal program... the list of features it lacks far exceeds the ones it has. However, it will allow you to check out a serial port. It's pretty easy to understand what it's up to if you read through the comments to the right of the assembly language. We'll have a proper look at what all the numbers mean starting next month.

You might have noticed that there's no obvious way to get out of this program. A proper terminal would probably provide an escape clause. In this case, being a test program, you can just hit control break to abort the look. It's inelegant, to be sure.

By the way, if you've been following the C language serial which has also been in this magazine over the past few months, you might be interested in seeing how this would be done in C. The following C program would result in much the same actual executing code when it was compiled. If you're into C, you might find this a lot easier to key in than the assembly language routines above.

```
/*setbaudrate*/
output(0x3fb,0x80);
output(0x3f8,0x80);
output(0x3f9,1);
output(0x3fb,0x1a);
```

```
/*terminalloop*/
do{
if(inport(0x3fd) & 0x01)
putch(inport(0x3f8));
if(kbhit())
output(0x3f8,getch());
}while(1);
```

Once again, we're counting on being

able to get out of the loop by hitting control break.

Next month we'll be looking at writing some actual drivers to make our serial port do its stuff elegantly and at reasonable speeds. ■

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