## Temperature-to-period circuit provides linearization of thermistor response

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Designers often use thermistors rather than other temperature sensors because thermistors offer high sensitivity, compactness, low cost, and small time constants. But most thermistors' resistance-versus-temperature characteristics are highly nonlinear and need correction for applications that require a linear response. Using a thermistor as a sensor, the simple circuit in Figure 1 provides a time period varying linearly with temperature with a nonlinearity error of less than 0.1K over a range as high as 30K. You can use a frequency counter to convert the period into a digital output. An approximation derived from Bosson's Law for thermistor resistance,  $R_{T}$ , as a function of temperature,  $\theta$ , comprises  $R_T = AB^{-\theta}$  (see sidebar "Exploring Bosson's Law and its equation" on the Web version of this article at www. edn.com/051110di1). This relationship closely represents an actual thermistor's behavior over a narrow temperature range.

You can connect a parallel resistance,  $R_p$ , of appropriate value across the thermistor and obtain an effective resistance that tracks fairly close to  $AB^{-\theta} \approx 30$ K. In **Figure 1**, the network connected between terminals A and B provides an effective resistance of  $R_{AB} \approx AB^{-\theta}$ . JFET  $Q_1$  and resistance  $R_s$  form a current regulator that supplies a constant current sink,  $I_s$ , between terminals D and E.

Through buffer-amplifier IC<sub>1</sub>, the voltage across  $R_4$  excites the RC circuit comprising  $R_1$  and  $C_1$  in series, producing an exponentially decaying voltage across  $R_1$  when  $R_2$  is greater than  $R_{AB}$ . At the instant when the decaying voltage across themistor  $R_T$ , the output of comparator IC<sub>2</sub> changes its state. The circuit oscillates, producing the voltage waveforms in **Figure 2** at

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IC<sub>2</sub>'s output. The period of oscillation, T, is  $T=2R_1C_1ln(R_2/R_{AB})\simeq 2R_1C_1$ [ln(R<sub>2</sub>/A)+ $\theta$ lnB]. This equation indicates that T varies linearly with thermistor temperature  $\theta$ .

You can easily vary the conversion sensitivity,  $\Delta T/\Delta \theta$ , by varying resistor  $R_1$ 's value. The current source comprising  $Q_1$  and  $R_1$  renders the output period, T, largely insensitive to variations in supply voltage and output load. You can vary the period, T, without affecting conversion sensitivity by



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varying  $R_2$ . For a given temperature range,  $\theta_L$  to  $\theta_{H^{1}}$  and conversion sensitivity,  $S_C$ , you can design the circuit as follows: Let  $\theta_C$  represent the center temperature of the range. Measure the thermistor's resistance at temperatures  $\theta_L$ ,  $\theta_C$ , and  $\theta_{H^{*}}$ . Using the three resistance values  $R_L$ ,  $R_C$ , and  $R_H$ , determine  $R_p$ , for which  $R_{AB}$  at  $\theta_C$  represents the geometric mean of  $R_{AB}$  at  $\theta_L$  and  $\theta_H$ . For this value of  $R_p$ , you get  $R_{AB}$  exactly equal to  $AB^{-\theta}$  at the three temperatures,  $\theta_1$ ,  $\theta_C$ , and  $\theta_H$ .

At other temperatures in the range,  $R_{_{AB}}$  deviates from  $AB^{-\theta},$  causing a nonlinearity error that is appreciably less than 0.1K for most thermistors when the temperature range is 30K or less. You can easily compute  $R_p$  using:  $R_{p} = R_{C}[R_{C}(R_{T} + R_{H}) - 2R_{L}R_{H}]/(R_{L}R_{H} - 2R_{L}R_{H})/(R_{L}R_{H} - 2R_{L}R_{$  $R_{c}^{2}$ ). Because temperature-to-periodconversion sensitivity,  $S_c$ , is  $2R_1$  $C_1$  lnb, you can choose  $R_1$  and  $C_1$  such that  $R_1C_1 = S_C[\theta_H - \theta_C]/\ln(R_{AB} \text{ at } \theta_I)$  $R_{AB}$  at  $\theta_{H}$ ) to obtain the required value of  $S_c$ . To get a specific output period,  $T_1$ , for the low temperature,  $\theta_1$ ,  $R_2$ should equal ( $R_{AB}$  at  $\theta_L$ )e<sup>Y</sup>, in which Y represents  $(T_1/2R_1C_1)$ . In practice, use a lower value for  $R_2$  because the nonzero response delay of IC, causes an increase in the output period.

Next, set potentiometers  $R_1$  and  $R_2$ close to their calculated values. After you adjust  $R_1$  for the correct  $S_C$ , adjust  $R_2$  until T equals  $T_L$  for temperature  $\theta_L$ . The two voltage-divider resistances,  $R_3$ and  $R_4$ , should be equal in value and of





close tolerances. As a practical example, use a standard thermistor, such as a Yellow Springs Instruments 46004, to convert a temperature span of 20 to 50°C into periods of 5 to 20 msec. This thermistor exhibits resistances for R<sub>L</sub>, R<sub>C</sub>, and R<sub>H</sub> of 2814, 1471, and 811.3 $\Omega$ , respectively, at the low, midpoint, and high temperatures. Other parameters for the design include S<sub>C</sub>=0.5 msec/K,  $\theta_L$ =20°C,  $\theta_H$ =50°C,  $\theta_C$ =35°C, and T<sub>1</sub>=5 msec.

Because only a fraction of current  $I_S$  is through the thermistor,  $I_S$  should be low to avoid self-heating effects. This design uses an  $I_S$  of approximately 0.48 mA, which introduces a self-heating error of less than 0.03K for a thermis-

tor's dissipation constant of 10 mW/K. Figure 1 illustrates the values of the components in the example. All resistors are of 1% tolerance and 0.25W rating; use a polycarbonate-dielectric capacitor for  $C_1$ .

Simulating various temperatures from 20 to 50°C by replacing the thermistor with standard, 2814 to 811.3 $\Omega$ , 0.01%-tolerance resistors produces T values of 5 to 20 msec with a maximum deviation from correct readings of less than 32 µsec, which corresponds to a maximum temperature error of less than 0.07K. Using an actual thermistor produces a maximum error of less than 0.1K for a thermistor dissipation constant of 10 mW/K or less.EDN